

## DEVICE FOR FIXING THIN AND FLEXIBLE SUBSTRATES

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### BACKGROUND OF THE INVENTION

#### 1. Field of the Invention

The present invention relates to a device or chuck or a  
10 clamping device for fixing thin and/or flexible  
substrates.

#### 2. Brief Description of Related Developments

15 One of the main objects of a mask aligner is the  
positioning and above all fixing of the mask and the  
substrate for being able to carry out a successful  
exposure process. The substrate is fixed on a specific  
device, a so-called chuck, which, via specifically  
20 arranged vacuum channels, sucks up and holds the  
substrate, e.g. a wafer, and thus allows the subsequent  
alignment, i.e., the adjustment of the mask and the  
substrate with respect to each other.

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### SUMMARY OF THE INVENTION

An example for the surface of such a known chuck 100 is  
shown in Figure 1. The vacuum channels 101 are formed  
as concentric circles, and a plurality of radial  
30 channels 102 connect the circularly arranged channels  
101 with each other. Moreover, the chuck has holes 103  
or notches which are connected with a vacuum device

(not shown) and through which the air can be sucked off so that a vacuum can be generated in the channels covered by the wafer.

5 In addition to the common silicon wafers, in industry recently more and more other, thin and flexible substrates are used, e.g. in the field of tape automatic bonding (TAB) or for the application in flexible flat panel displays. In order to be able to  
10 suck up these substrates in an optimum manner, new technologies are required.

The problems concerned with sucking up flexible substrates generally reside in that these substrates  
15 tend to warp and twist and have a certain basic waviness. In the field of TAB, an additional edge waviness of the substrate occurs due to the use of protective foils or sheets being inserted between the rolled-up layers of the Cu tapes to be processed.

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If such substrates are fixed with the aid of conventional chucks by sucking up, there is the risk that the surfaces of the substrates lying above a vacuum channel or a notch are sucked into the notch due  
25 to their low stiffness and thickness so that an additional waviness of the substrate surface is caused. On the one hand, this leads to an irregular alignment distance and above all exposure distance, on the other hand there is the risk that - at the alignment and/or  
30 exposure distance - the substrates contact, spoil or even destroy the mask. For these reasons, it is not advisable to suck up flexible substrates punctually

over wide notches or holes with a great suction force.

A device according to the preamble of claim 1 is known  
from EP 0 595 071 A1 and the corresponding DE 693 22  
5 835 T2.

It is the object of the invention to provide a device  
or chuck for fixing thin and/or flexible substrates,  
thereby allowing a uniform and all-over sucking up of  
10 the substrates without any disadvantageous warping or  
bending.

This object is achieved with the features of the  
claims.

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In achieving this object, the invention is based on the  
general idea to provide a plurality of microgrooves,  
which are produced by means of a suitable tool, on the  
bearing surface of the chuck. Moreover, the device of  
20 the invention comprises notches and/or holes which  
communicate with the microgrooves and via which air is  
sucked off by means of a vacuum device in order to  
generate a vacuum in the microgrooves when the  
substrate is put on the chuck.

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In addition, the channels can take up dirt particles  
which are probably present on the lower surface of the  
substrate, so that these dirt particles do not  
deteriorate the flatness of the put-on substrate.

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## BRIEF DESCRIPTION OF THE DRAWINGS

In the following, the invention will be described in more detail on the basis of working examples and with  
5 reference to the drawing in which

Figure 1 schematically shows the surface of a conventional chuck;

10 Figure 2 is a schematic side view of a device according to the invention;

Figures 3(a) and (b) are schematic top views of the bearing surface of the device in the direction of the  
15 arrow A in Figure 2 in two alternative embodiments; and

Figure 4 is a schematic cross-section B-B of the bearing surface of Figure 3(a).

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## DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT(S)

Figure 2 is a schematic side view of the device according to the invention for fixing a substrate 3.  
25 The substrate 3 is arranged on the flat bearing surface 2 of the holding device 1. In its bearing surface 2, the holding device 1 has notches 4 which are connected with each other and, via holes 5, with a vacuum device 6, e.g., in the form of a vacuum channel.

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For example, a suction opening 8 is connected with a vacuum pump (not shown) so that air can be sucked off

via the vacuum channel 6 and through the holes 5 and the notches 4. Depending on the size of the substrate 3 to be sucked up, preferably only a part of the notches 4 and/or holes 5 can be connected with the suction opening 8.

Moreover, a plurality of microgrooves 7 are engraved into the bearing surface 2 of the holding device 1. These microgrooves 7 communicate with the notches 4 and/or holes 5 serving as the vacuum supply. By sucking off air via the vacuum device 6, a vacuum is generated in the microgrooves 7 when the substrate 3 is put on, said vacuum sucking up the substrate 3 onto the bearing surface 2.

Figure 3(a) is a schematic top view of the bearing surface 2 without the substrate to be fixed. In the shown embodiment, the microgrooves 7 are arranged in the form of segments of a circle. The radius of the segments of the circle is, e.g., 40 to 100 mm, preferably 60 to 80 mm, particularly preferably 70 mm. The notches 4 are shaped as slots extending transversely with respect to the microgrooves 7 and have a length of, e.g., 1.5 cm and a width of, e.g., 0.5 mm. Due to this arrangement, essentially all microgrooves 7 communicate with at least one notch 4 through which air is sucked in.

In Figure 3(a), like in Figure 3(b), which will be discussed in the following, only a part of the actually present microgrooves 7 is drawn in, in order to improve clarity. These microgrooves 7 are preferably

distributed regularly or uniformly on the entire bearing surface 2 (or on a large part thereof).

Figure 4 is a schematic cross-sectional view of the bearing surface 2 of the device of the invention along the line B-B in Figure 3(a). The microgrooves 7 have a depth of 30 to 70  $\mu\text{m}$ , preferably of 40 to 60  $\mu\text{m}$ , particularly preferably of 50  $\mu\text{m}$  and a width of 80 to 160  $\mu\text{m}$ , preferably of 100 to 140  $\mu\text{m}$ , particularly preferably of 120  $\mu\text{m}$ . The distance between the individual grooves is, e.g., 0.1 to 0.2 mm, preferably 0.15 mm.

If the substrate 3 is put on and if air is sucked in through the notches 4 and/or holes 5, a vacuum is generated in the microgrooves 7 extending from the supply notches 4. The plurality of microgrooves 7 and their small channel widths make it possible that the substrate 3 lying thereon is sucked up more or less all-over its surface. In a preferred embodiment, the relationship between bearing surface and sucking-up surface is about 1:3 and establishes the fact that the substrate 3 is sucked up very well. Due to the small widths of the indentations, i.e. the notches 4 and the microgrooves 7, the substrate 3 deforms only very little during the sucking up process.

A further advantage of the small cross-section of the microgrooves 7 is the fact that at the edge of the substrate 3 and at probably present recesses in the substrate 3 only very little air is sucked up so that the vacuum leakage is negligible. Thus, the substrate

is optimally sucked up even in the area of holes, which are probably present at the edge, due to the large number and the small cross-section of the microgrooves 7.

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Figure 3(b) is a top view of an alternative embodiment of the bearing surface 2. This embodiment differs from the embodiment shown in Figure 3(a) only in the arrangement of the notches 4. The substrate 3 to be  
10 fixed is exemplarily shown as a rectangle but can have any desired shape. The substrate 3 has a use surface 31. The use surface 31 is the area of the substrate 3 which is exposed during the later exposure process. The supply notches 4 are arranged such that they are  
15 covered by the substrate, so that the vacuum necessary for the fixing can be generated in the microgrooves 7, but do not lie within the area of the use surface 31. It can thus be ensured that even if the substrate 3 is sucked into the notches 4, which have a greater width  
20 than the microgrooves 7, the thus generated waviness of the substrate surface occurs only outside the use surface 31 so that a regular alignment and exposure distance is assured in the area of the use surface 31. The arrangement of the notches 4 can be optimized  
25 depending on the shape and size of the substrate 3 in such a way that an as large as possible use surface 31 is present.

In the shown embodiments the microgrooves 7 have a  
30 circular shape; within the scope of the invention, they can also have a straight, elliptic, parabolic or any desired shape, wherein it must only be assured that

with a given substrate and given dimensions of the microgrooves (e.g. width, depth and distance from the neighboring microgroove), the substrate is sucked up sufficiently without any disadvantageous warping.

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For producing the microgrooves 7 on the bearing surface 2 of a chuck according to the present invention, for example a turning tool or chisel is used which, e.g., has a cutting edge being made of hard metal and having  
10 a radius of 0.2 mm. The further characteristic data according to DIN 6581 of a turning tool are, for example: relief angle  $\alpha = 6^\circ$ , wedge angle  $\beta = 80^\circ$ , rake angle  $\gamma = 4^\circ$ , edge angle  $\epsilon_r = 45^\circ$ , adjustment angle  $K_r = 90^\circ$  and inclination angle  $\lambda_r = 1^\circ$ .

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The turning tool is clamped in a vertical head of a milling machine, so that the turning tool performs a rotary movement during machining. The radius of the movement and thus of the milled structures is  
20 preferably about 70 mm. The chuck is clamped in such a manner that the microengravings 7 are milled vertically with respect to the transport direction of the substrate. The spindle speed is about 500 revolutions/minute and the feed is about 40 mm/minute.  
25 After the milling operation, the surface of the chuck is preferably treated by grinding or lapping in order to obtain again a flat bearing surface. Finally, the surface of the chuck can be eloxed black or provided with a hard coating.

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What is claimed is: